Report for 15th December

Anish and Venkata sai

* Sorted out the connections between the ME1616 and Kelly controller
* Made the circuit diagram.
* We tried to figure out the throttle wiring but haven’t figured out
* Made the list of required components in LVS and the HVS.
* Tried to run the old motor of MM01 but as we couldn’t figure the connections for the throttle.
* Made a speedometer using GPS module and found few alternatives for the speedometer display.
* Gathered the specs of ME1616 for the Orion software.
* Found a way to connect 7pin (ME1616 Motor) to 6pin(ECU).
* Read about the CAN.

A white paper with writing on it

Description automatically generated with low confidence